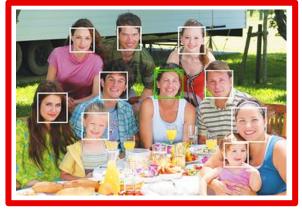
# **Development of intelligent systems** (RInS)

# **Object detection**

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## **Computer vision**



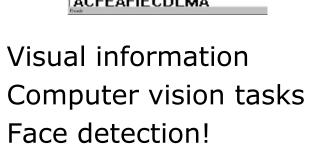


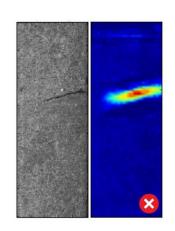


















#### **Classification**

What is depicted in the image?

Categorisation





Recognition/identification of instances





#### Localisation



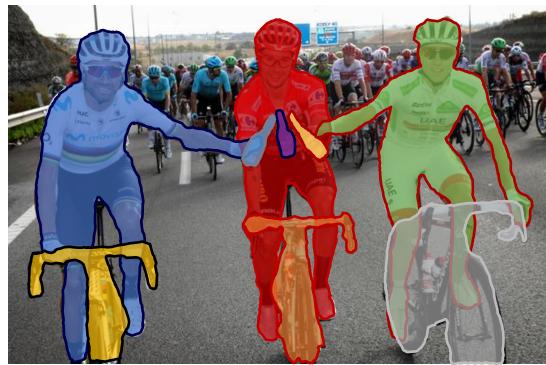
### **Detection**

## Where in the image?

#### Detection



## Instance segmentation



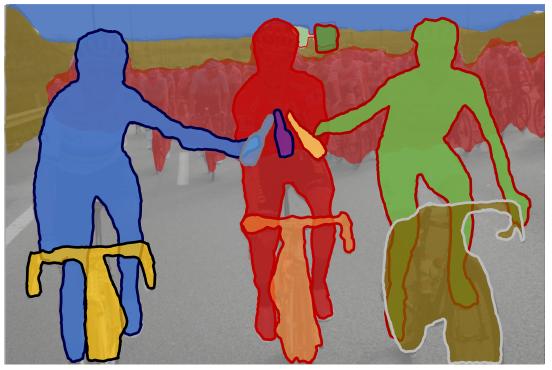
# **Segmentation**

What does every pixel represent?

Semantic segmentation



Panoptic segmentation

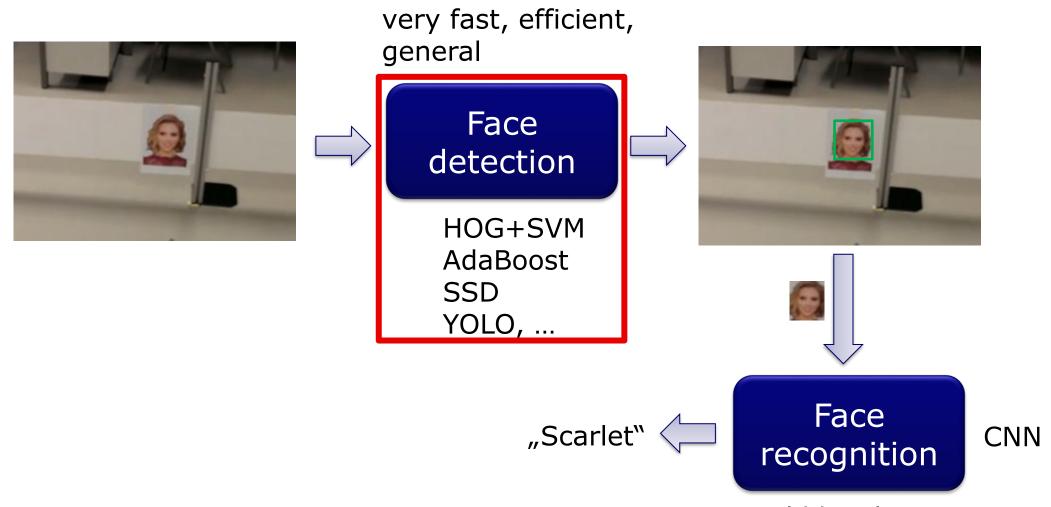


#### **Face detection**

Find and localise all faces in the image.



# Two stage object detection and recognition



could be slower, computationally more complex, specific

#### **Observation model**

- Several face detectors available
  - HOG+SVM
  - AdaBoost
  - SSD
  - YOLO
  - Any other?
- Not perfect
- Which one is better?
  - More true positives
  - Less false positives
- Test set
  - Images, videos
  - Different angles, illumination
  - Motion blur, etc.
- Observation model
  - Performance
    - at different distances and angles
    - at different illuminations

#### Robustification of detection

- Use and robustify the better detector
- Take into account temporal dimension
  - Repetitive detections more robust
  - Filter out false positives
- Take into account spatial dimension
  - Non-maximum suppression
  - Observation model

- Map the image from 2D image to 3D world
- Anchor the image into the map
- Non-maximum suppression in the map
- Redetection of faces from different directions



#### **Face detection**

