

# 1. naloga

a)

$$R_{n1} = R_1 + R_2 = 2.5\Omega, \quad R_{n2} = R_3 + R_2 = 1.5\Omega, \quad R_{n3} = \frac{R_{n1} \cdot R_{n2}}{R_{n1} + R_{n2}} = 0.9375\Omega$$

$$R_n = R_{n3} + R_4 = 1.0375\Omega$$

**Rezultat: 2T**

b)

$$I_0 = \frac{U_0}{R_n} = 4.819A \quad \mathbf{2T}$$
$$I_2 = \frac{U_{n2}}{R_{n2}} = \frac{U_0 - U_4}{R_{n2}} = \frac{U_0 - R_4 \cdot I_0}{R_{n2}} = \frac{5V - 0.1\Omega \cdot 4.819A}{1.5\Omega} = 3.012A \quad \mathbf{1T}$$
$$I_1 = \frac{U_{n1}}{R_{n1}} = \frac{U_0 - U_4}{R_{n1}} = \frac{U_0 - R_4 \cdot I_0}{R_{n1}} = \frac{5V - 0.1\Omega \cdot 4.819A}{2.5\Omega} = 1.807A \quad \mathbf{1T}$$

Ali iz K.Z.

$$1: I_1 + I_2 = I_0, \quad I_0 = \frac{U_0}{R_n} = 4.819A \quad \mathbf{2T}$$
$$2: U - I_0 R_4 - I_2 (R_3 + R_2) = 0, \quad 3: U - I_0 R_4 - I_1 (R_1 + R_2) = 0$$
$$2: I_2 = \frac{U - I_0 R_4}{R_3 + R_2} = 3.012A, \quad 3: I_1 = \frac{U - I_0 R_4}{R_1 + R_2} = 1.807A$$

**Enačba I<sub>2</sub> ali I<sub>1</sub>: 2T**

**Rezultat: 1T+1T**

c)

$$P = U \cdot I = U_4 \cdot I_0 = 2.32W$$

### 3. naloga

a)

$$\Delta W = 0, \quad \Delta W_k + \Delta W_{ep} = 0, \quad W_k^k - W_k^z + W_{ep}^k - W_{ep}^z = 0, \quad \frac{mv^2}{2} = eU$$

$$v = \sqrt{\frac{2eU}{m}}, \quad v(^3He^+) = 254 \cdot 10^3 m/s$$

b)

$$ma_c = evB, \quad a_c = \frac{v^2}{R}, \quad R = \frac{mv}{eB}, \quad D = 2R(^3He^+) = 2 * 7,15 cm = 14,3 cm$$

c)

$$v(^4He^+) = 219,7 \cdot 10^3 m/s, \quad D_2 = 2R(^4He^+) = 2 * 8,3 cm = 16,6 cm$$

$$\Delta D = 2,3 cm$$

### 5. naloga

$$F = IlB = l \frac{I_1 I_2 \mu_0}{2\pi r}, \quad \frac{F(r)}{l} = -\frac{I^2 \mu_0}{2\pi r}, \quad F = ma = m\ddot{r}, \quad \frac{F}{l} = \lambda \ddot{r},$$

$$\ddot{r} = -\left(\frac{I^2 \mu_0}{2\pi \lambda}\right) \frac{1}{r} = -A \frac{1}{r}, \quad \frac{d^2 r}{dt^2} = \frac{dv}{dt} = \frac{dv}{dr} \frac{dr}{dt} = -A \frac{1}{r}$$

$$v dv = -\frac{A dr}{r} \int$$

$$\int_0^v v' dv' = -A \int_{r_0}^r \frac{dr'}{r'}, \quad \frac{v^2}{2} \Big|_0^v = -A \ln r \Big|_{r_0}^r, \quad \frac{v^2}{2} = -A \ln \frac{r}{r_0}$$

$$v(r) = \pm \sqrt{-2A \ln r / r_0}, \quad v(r) = -I \sqrt{-\frac{\mu_0}{\pi \lambda} \ln \frac{r}{r_0}}$$

Ali

$$F = IlB = l \frac{I_1 I_2 \mu_0}{2\pi r}, \quad A = \Delta W_k, \quad A = \int F dr, \quad W_k^{konč} = \int F dr$$

$$\frac{mv^2}{2} = -\frac{I^2 \mu_0 l}{2\pi} \int_{r_0}^r \frac{dr'}{r'}, \quad \frac{v^2}{2} = -\frac{I^2 \mu_0}{2\pi \lambda} \ln r \Big|_{r_0}^r, \quad \frac{v^2}{2} = -A \ln \frac{r}{r_0}$$

Meje: 2T

## 2. naloga

$$F_{el} = \frac{e_1 e_2}{4\pi\epsilon_0 r^2} \quad (2T)$$

$$F_2 = F_3 = \frac{2e_1^2}{4\pi\epsilon_0 a^2} = 180N \quad (2T)$$

$$F_4 = \frac{-3e_1^2}{8\pi\epsilon_0 a^2} = -135N \quad (2T)$$

$$F_{REZ} = \frac{4\sqrt{2} - 3}{2} \frac{e_1^2}{4\pi\epsilon_0 a^2} = 120N \quad (5 + 2T)$$

$$F_{REZ} \text{ direction} \rightarrow (\cos 135^\circ, \sin 135^\circ) \quad (2T)$$

$$A = W_K - W_Z \quad (3T)$$

$$W_Z = \frac{e_1 e_2}{4\pi\epsilon_0 a} + \frac{e_1 e_3}{4\pi\epsilon_0 a} + \frac{e_1 e_4}{4\pi\epsilon_0 \sqrt{2}a} + \frac{e_2 e_3}{4\pi\epsilon_0 \sqrt{2}a} + \frac{e_2 e_4}{4\pi\epsilon_0 a} + \frac{e_3 e_4}{4\pi\epsilon_0 a} \quad (2T)$$

$$W_K = \frac{e_1 e_2}{4\pi\epsilon_0 a} + \frac{e_1 e_3}{4\pi\epsilon_0 a} + \frac{e_2 e_3}{4\pi\epsilon_0 \sqrt{2}a} \quad (2T)$$

$$A = -\left(\frac{e_1 e_4}{4\pi\epsilon_0 \sqrt{2}a} + \frac{e_2 e_4}{4\pi\epsilon_0 a} + \frac{e_3 e_4}{4\pi\epsilon_0 a}\right) = 63.5J \quad (2 + 1T)$$

## 4. naloga

$$J_{palica} = \frac{m_P l^2}{3} \quad (2T)$$

$$J_{disk} = \frac{m_D R^2}{2} + m_D (l + R)^2 \text{ (drugačna os od težišča)} \quad (3T)$$

$$J = J_P + J_D = 3.76 \text{ kg m}^2 \quad (3 + 2T)$$

$$M = m_P g \frac{l}{2} \sin \phi + m_D g (l + R) \sin \phi + k \left(\frac{4l}{5}\right)^2 \sin \phi \cos \phi \quad (1 + 1 + 3T)$$

$$M \simeq \left(m_P g \frac{l}{2} + m_D g (l + R) + k \left(\frac{4l}{5}\right)^2\right) \phi \text{ (razvoj)} \quad (3T)$$

$$M = J\alpha \rightarrow \ddot{\phi} + \frac{M}{J} = 0 \quad (3T)$$

$$\ddot{\phi} + \frac{M}{J} = 0 \rightarrow \ddot{\phi} + \omega^2 \phi = 0 \text{ (dobimo } \omega) \quad (2T)$$

$$t_0 = \frac{2\pi}{\omega} = 2s \quad (2T)$$