

$$\checkmark = 3,125$$

1.

(a) $v(t) = v_0 + at$ ✓

$t_1 = 2,75 \rightarrow v(t_1) = 0 \text{ m/s} + 0,25 \text{ m/s}^2 \cdot 2,75 = 0,6875 \text{ m/s}$ ✓

$t_2 = 7,35 \rightarrow v(t_2) = 0,25 \text{ m/s}^2 \cdot 4 \text{ s} = 1 \text{ m/s}$

$v(7,35) = 1 \text{ m/s} - 0,75 \text{ m/s}^2 \cdot (7,35 - 4) = -1,475 \text{ m/s}$ ✓

(b) $x(t) = x_0 + v_0 t + \frac{at^2}{2}$ ✓, $t = 14,5 \text{ s}$

i) $t = 0 \rightarrow 4 \text{ s} : x(4 \text{ s}) = \frac{1}{2} 0,25 \text{ m/s}^2 \cdot (4 \text{ s})^2 = +2 \text{ m}$
 $v(4 \text{ s}) = 1 \text{ m/s}$

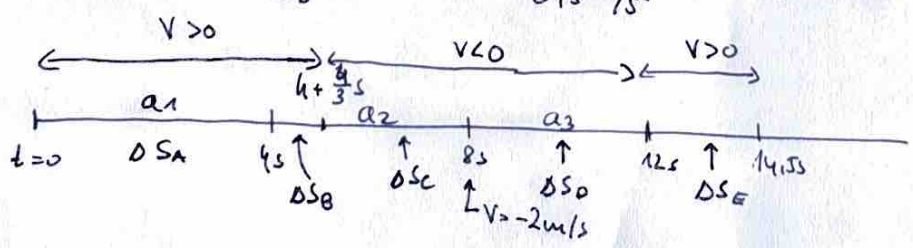
ii) $t = 4 \text{ s} \rightarrow 8 \text{ s} : x(8 \text{ s}) = 2 \text{ m} + 1 \text{ m/s} \cdot 4 \text{ s} - \frac{1}{2} 0,75 \text{ m/s}^2 \cdot (4 \text{ s})^2 = 0 \text{ m}$
 $v(8 \text{ s}) = 1 \text{ m/s} - 0,75 \text{ m/s}^2 \cdot 4 \text{ s} = -2 \text{ m/s}$

iii) $t = 8 \text{ s} \rightarrow 14,5 \text{ s} : x(14,5 \text{ s}) = 0 \text{ m} - 2 \text{ m/s} \cdot 6,5 \text{ s} + \frac{1}{2} 0,5 \text{ m/s}^2 \cdot (6,5 \text{ s})^2 = -2,44 \text{ m}$ ✓
 položaj.

Pot : telo spremeni smer gibanja (hitrost spremeni predznak) pri:

$v = at + v_0$
 $t' = -\frac{v(t)}{a_2} = -\frac{1 \text{ m/s}}{-0,25 \text{ m/s}^2} = +\frac{1}{3/4} \text{ s} = \frac{4}{3} \text{ s} \rightarrow \text{pri } 4 \text{ s} + \frac{4}{3} \text{ s}$

$t'' = -\frac{v(8 \text{ s})}{a_3} = -\frac{-2 \text{ m/s}}{0,5 \text{ m/s}^2} = +4 \text{ s} \rightarrow \text{pri } 8 \text{ s} + 4 \text{ s} = 12 \text{ s}$



$\Delta S_A = \frac{1}{2} 0,25 \text{ m/s}^2 \cdot (4 \text{ s})^2 = 2 \text{ m}$

$\Delta S_B = 1 \text{ m/s} \cdot \frac{4}{3} \text{ s} - \frac{1}{2} 0,25 \text{ m/s}^2 \cdot \left(\frac{4}{3} \text{ s}\right)^2 = \frac{2}{3} \text{ m}$

$\Delta S_C = 0 \text{ m/s} \cdot \frac{8}{3} \text{ s} - \frac{1}{2} 0,25 \text{ m/s}^2 \cdot \left(\frac{8}{3} \text{ s}\right)^2 = \frac{8}{3} \text{ m}$
 $(4 - \frac{4}{3}) \text{ s} = \frac{8}{3} \text{ s}$

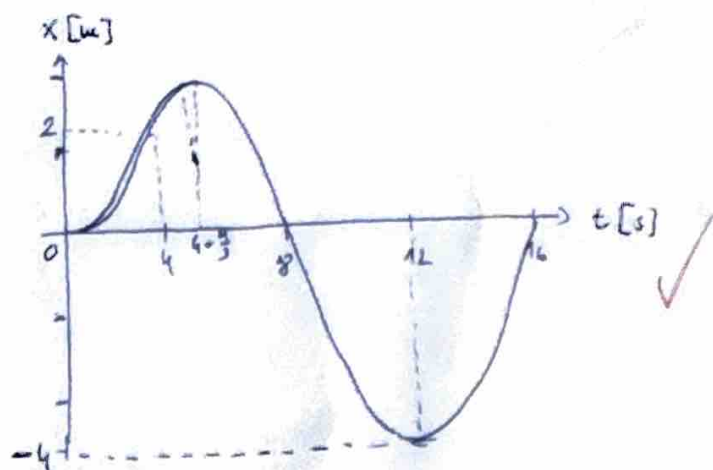
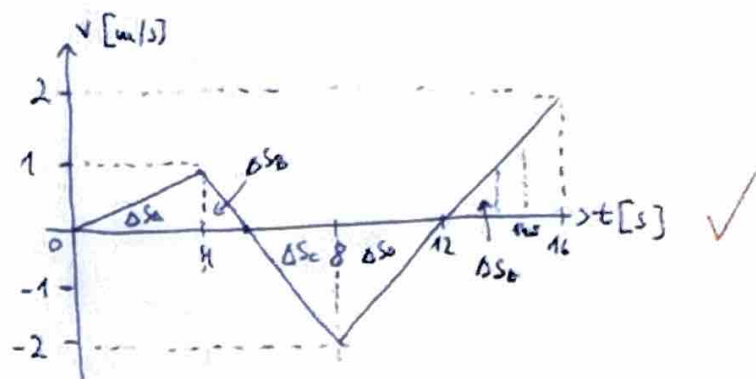
$\Delta S_D = | -2 \text{ m/s} \cdot 4 \text{ s} + \frac{1}{2} 0,5 \text{ m/s}^2 \cdot (4 \text{ s})^2 | = 4 \text{ m}$
 $\uparrow$
 $12 \text{ s} - 8 \text{ s}$

$\Delta S_E = 0 \text{ m/s} \cdot 2,5 \text{ s} + \frac{1}{2} 0,5 \text{ m/s}^2 \cdot (2,5 \text{ s})^2 = 1,56 \text{ m}$
 $14,5 \text{ s} - 12 \text{ s} = 2,5 \text{ s}$

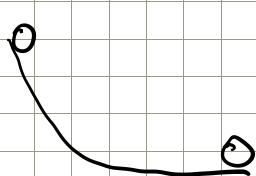
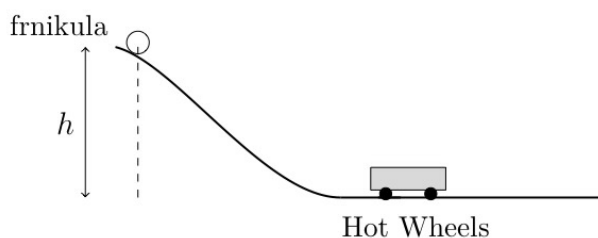
$S = \Delta S_A + \Delta S_B + \Delta S_C + \Delta S_D + \Delta S_E$
 $\approx 10,9 \text{ m}$ ✓

ALTERNATIVNO : Ploščina pod grafom $v(t)$

(c)



2. Frnikula z radijem 1 cm se brez spodrsavanja kotili po klancu. Ob vznožju klanca je parkiran Hot Wheels avtomobilček. Pri trku se avtomobilček in frnikula zlepi. Kako visoko (h) mora začeti frnikula, da je hitrost avtomobilčka po trku enaka 1,6 m/s? Masa frnikule znaša 20 g, masa avtomobilčka 30 g. Trenje zanemari.



ZOE:

$$Z: W_{\text{tot}}^{(Z)} = mgh \quad 3$$

$$K: W_{\text{tot}}^{(K)} = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2 \quad 3$$

kotaliziraj: $v = \omega r \quad 2$

$$I = \frac{2}{5}mr^2 \quad 2$$

$$W_{\text{tot}}^{(K)} = \frac{1}{2}mv^2 + \frac{1}{2} \cdot \frac{2}{5}mr^2 \cdot \omega^2$$

$$= \frac{1}{2}mv^2 + \frac{1}{5}mv^2 = \frac{7}{10}mv^2$$

$$mgh = \frac{7}{10}mv^2 \Rightarrow v = \sqrt{\frac{10}{7}gh} \quad 2$$

reprezentni trk:

$$Z: G_{\text{tot}}^{(Z)} = mvr + m_H \cdot 0 \quad 3$$

$$K: G_{\text{tot}}^{(K)} = (m + m_H)v' \quad 3$$

ZOK: $mvr = (m + m_H)v'$

$$v' = \frac{m}{m + m_H} v \quad 2$$

Zoklaj:

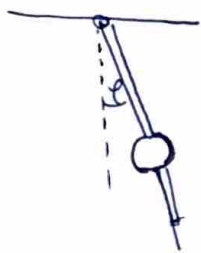
$$v' = \frac{m}{m + m_H} \sqrt{\frac{10}{7}gh} \quad \text{in izrazimo } h$$

$$v'^2 = \left(\frac{m}{m + m_H} \right)^2 \frac{10}{7}gh$$

$$h = \left(\frac{m + m_H}{m} \right)^2 \cdot \frac{7}{10} \cdot \frac{1}{g} \cdot v'^2 \quad 3$$

$$h = \left(\frac{50g}{20g} \right)^2 \cdot \frac{7}{10} \cdot \frac{s^2}{10m} \cdot \left(1.6 \frac{m}{s} \right)^2 = \underline{\underline{1.12m}} \quad 2$$

3.



$$M_p = -m_p g \frac{l}{2} \sin \varphi \quad \checkmark$$

$$M_u = -m_u g l' \sin \varphi \quad \checkmark$$

$$J_p = \frac{1}{3} m_p l^2 \quad \checkmark$$

$$J_u = \frac{2}{5} m_u r^2 + m_u l'^2 \quad \checkmark$$

$$J_d = M \quad \checkmark$$

$$\alpha = \frac{d^2 \varphi}{dt^2} = - \frac{m_p g \frac{l}{2} \sin \varphi + m_u g l' \sin \varphi}{\frac{1}{3} m_p l^2 + \frac{2}{5} m_u r^2 + m_u l'^2}$$

$$\sin \varphi \approx \varphi$$

$$\frac{d^2 \varphi}{dt^2} = - \underbrace{\frac{m_p g \frac{l}{2} + m_u g l'}{\frac{1}{3} m_p l^2 + \frac{2}{5} m_u r^2 + m_u l'^2}}_{= \omega^2} \varphi$$

$$\omega^2 = + \frac{m_p g \frac{l}{2} + m_u g l'}{\frac{1}{3} m_p l^2 + \frac{2}{5} m_u r^2 + m_u l'^2} \quad \checkmark (*)$$

$$\omega^2 \left(\frac{1}{3} m_p l^2 + \frac{2}{5} m_u r^2 + m_u l'^2 \right) = m_p g \frac{l}{2} + m_u g l'$$

$$\frac{1}{3} m_p l^2 \omega^2 + \omega^2 \left(\frac{2}{5} r^2 + l'^2 \right) m_u = m_p g \frac{l}{2} + m_u g l'$$

$$m_u \cdot \omega^2 \left(\frac{2}{5} r^2 + l'^2 \right) - m_u g l' = m_p g \frac{l}{2} - \frac{1}{3} m_p l^2 \omega^2$$

$$m_u \left[\omega^2 \left(\frac{2}{5} r^2 + l'^2 \right) - g l' \right] = m_p g \frac{l}{2} - \frac{1}{3} m_p l^2 \omega^2$$

$$m_u = \frac{m_p g \frac{l}{2} - \frac{1}{3} m_p l^2 \omega^2}{\omega^2 \left(\frac{2}{5} r^2 + l'^2 \right) - g l'} \quad \checkmark, \quad \omega = \frac{2\pi}{T}$$

$$= \frac{0.1 \text{ kg} \cdot 10 \frac{\text{m}}{\text{s}^2} \cdot \frac{1.05 \text{ m}}{2} - \frac{1}{3} 0.1 \text{ kg} \cdot (1.05 \text{ m})^2 \cdot \left(\frac{2\pi}{1.15 \text{ s}} \right)^2}{\left(\frac{2\pi}{1.15 \text{ s}} \right)^2 \left[\frac{2}{5} (0.05 \text{ m})^2 + (0.6 \text{ m})^2 \right] - 10 \frac{\text{m}}{\text{s}^2} \cdot (0.6 \text{ m})} =$$

$$= \begin{cases} 0.106 \text{ kg} \approx g = 9.8 \text{ m/s}^2 \\ 0.109 \text{ kg} \approx g = 10 \text{ m/s}^2 \end{cases}$$

ALTERNATIVNO: φ_{max}

$$\omega = \sqrt{\frac{m g r^*}{J}} \quad \checkmark \Rightarrow \omega^2 = \frac{g (m_p + m_u) \frac{m_p \frac{l}{2} + m_u l'}{m_p + m_u}}{\frac{1}{3} m_p l^2 + \frac{2}{5} m_u r^2 + m_u l'^2} =$$

$$m = m_p + m_u \quad \checkmark$$

$$r^* = \frac{m_p \frac{l}{2} + m_u l'}{m_p + m_u} \quad \checkmark$$

↑
položaj težišća

$$J = \frac{1}{3} m_p l^2 + \frac{2}{5} m_u r^2 + m_u l'^2$$

$$\omega^2 = \frac{(m_p \frac{l}{2} + m_u l') g}{\frac{1}{3} m_p l^2 + \frac{2}{5} m_u r^2 + m_u l'^2} \quad (*)$$

evalo
necpraj

NI DELA ZUNANJIH SIL $\Rightarrow$ ENERGIJA SE OHRANJA

$$\Delta W_{p,u} + \Delta W_{g,u} + \Delta W_{p,g} + \Delta W_{rot} = 0 \quad 5$$

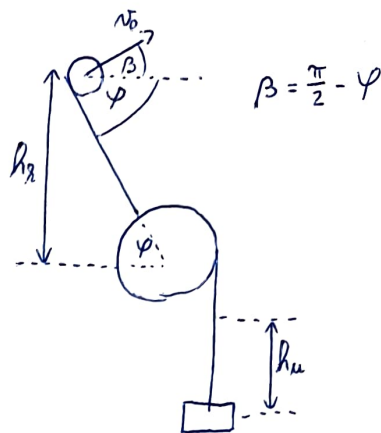
$$-m_u g h_u + \frac{m_u v_u^2}{2} + m_g g h_g + \frac{J \omega^2}{2} = 0 \quad (1)$$

$$h_u = R \varphi / \frac{d}{dt}$$

$$h_g = (R+l) \sin \varphi$$

$$v_u = R \omega \quad 3$$

$$J = \frac{1}{2} m_v R^2 + m_g (R+l)^2 \quad 3$$



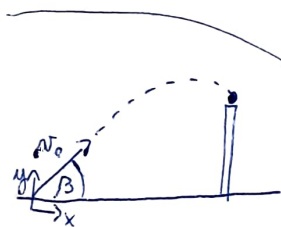
ZANIMA NAS HITROST $v_o = (R+l) \omega$

$$(1): -m_u g R \varphi + \frac{m_u R^2 \omega^2}{2} + m_g g (R+l) \sin \varphi + \frac{J \omega^2}{2} = 0$$

$$\omega^2 \left[\frac{1}{2} m_u R^2 + \frac{1}{2} J \right] = m_u g R \varphi - m_g g (R+l) \sin \varphi$$

$$\omega^2 = \frac{2g(m_u R \varphi - m_g (R+l) \sin \varphi)}{m_u R^2 + \frac{1}{2} m_v R^2 + m_g (R+l)^2} \quad 3$$

$$\Rightarrow v_o = (R+l) \sqrt{\frac{2g[m_u R \varphi - m_g (R+l) \sin \varphi]}{m_u R^2 + \frac{1}{2} m_v R^2 + m_g (R+l)^2}}$$



X-mer:

$$x = v_o \cos \beta t \Rightarrow t = \frac{x}{v_o \cos \beta} \quad 3$$



$$v_o = 11,18 \frac{m}{s} \quad 1$$

y-mer:

$$y(t) = v_o \sin \beta t - \frac{g t^2}{2} \xrightarrow{\text{vstavimo}} y(x) = v_o \sin \beta \frac{x}{v_o \cos \beta} - \frac{g x^2}{2 v_o^2 \cos^2 \beta}$$

$$y(x) = x \tan \beta - \frac{g}{2 v_o^2 \cos^2 \beta} x^2 \quad 3$$

$$y(d) = d \tan \left(\frac{\pi}{2} - \varphi \right) - \frac{g}{2 v_o^2 \cos^2 \left(\frac{\pi}{2} - \varphi \right)} d^2$$

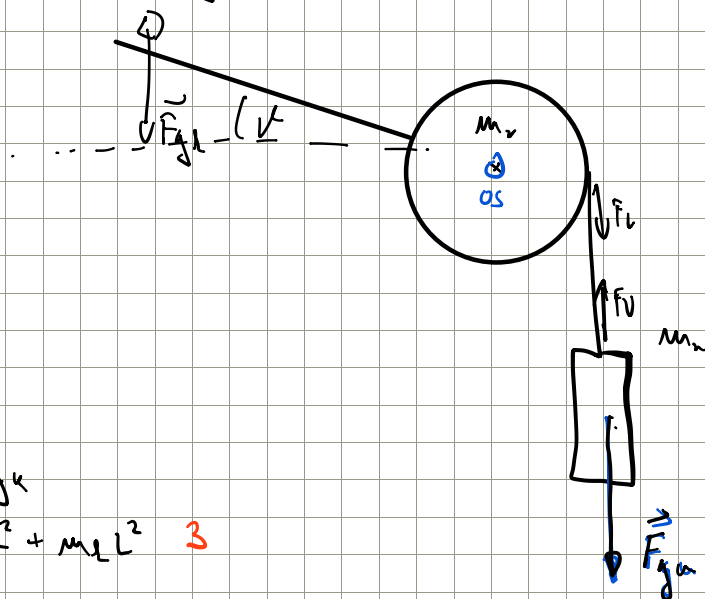
$$y(d) = -2,98 \text{ m}$$

POD VIŠINO OBZIDJA

$\Rightarrow$ KAMEN NE PRIDE ČEZ OBZIDJE 1

alt. reševanje z naravnimi

2 N2N: $\sum M = J \alpha$



$$J = J_v + J_k$$

$$= \frac{1}{2} m_v R^2 + m_v L^2 \quad 3$$

enake za utei: ($F = ma$)

$$m_n g - F_v = m_n R \ddot{\varphi} \quad 3$$

enake za rotirajoče telo ($M = J \alpha$)

$$F_v R - m_v g L \cos \theta = J \ddot{\varphi} \quad 3$$

se znešimo F_v

in dobimo:

$$m_n g - m_v g L \cos \theta = (J + m_n R^2) \ddot{\varphi} \quad 3$$

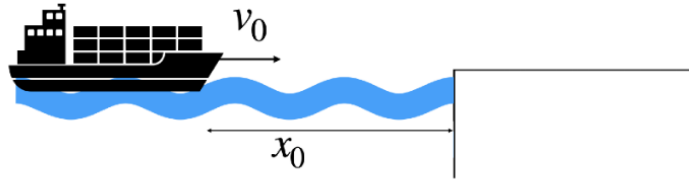
Diferencialne enačbe $\rightarrow$ rešujemo z energijami!

te pike so v primeru, ko se študent
vpečeno odloči uporabiti naravne
energije

5. Tanker Kobayashi Maru se približuje pristanišču v Kopru z začetno hitrostjo $v_0 = 11 \text{ m/s}$. Ko izključi motorje, se tankerjev pojemek spreminja kot $a = -k v$, kjer je $k = 2.5 \text{ /s}$.

a) Po kolikem času pade hitrost tankerja na $v = 1.1 \text{ m/s}$?

b) Koliko stran, x_0 , od pomola mora tanker ugasniti motor, da v pomol zadane s hitrostjo manjšo kot 1.1 m/s ?



a) Po kolikem času se njegova hitrost zmanjša za $10\times$?

$$a = \frac{dv}{dt} = -k v \quad 3$$

$$\int_{v_0}^v \frac{dv}{v} = \int_0^t -k dt \quad 2$$

$$\ln v = -kt$$

$$\ln v \Big|_{v_0}^v = -kt$$

$$\ln\left(\frac{v}{v_0}\right) = -kt$$

$$-\ln 10 = -kt \quad 5$$

$$t = \ln 10 / k = 0.92 \text{ s} \quad 2$$

b) Koliko stran od pomola, mora tanker ugasniti motor, da v pomol zadane s hitrostjo manjšo od 1.1 m/s ?

$$v(t) \Rightarrow \ln v \Big|_{v_0}^v = -kt \Big|_0^t$$

$$\ln \frac{v}{v_0} = -kt \Rightarrow v = v_0 e^{-kt} \quad 3$$

$$x(t) = \int_0^t v(t) dt$$

$$x(t) = v_0 \int_0^t e^{-kt} dt = \frac{v_0}{-k} e^{-kt} \Big|_0^t = \frac{v_0}{-k} (e^{-kt} - 1) \quad 5$$

$$x(t) = \frac{v_0}{-k} (e^{-kt} - 1) = 3.96 \text{ m} \quad 2 \quad 3$$