

Assignment 4

Implement the following three algorithms described below. Each algorithm is worth up to five points. Solutions must be submitted by 19.5.2024. Use the link on e-ucilnica to turn in your work. The report must be in .pdf format with provided .py file for code submission.

Continuous optimization

This assignment is an introduction to continuous optimization using functions available in *pymoo* python package. This is also a warm-up for the Assignment 5. By completing this you should have a groundwork for starting next assignment.

The assignment consists of finding values at specific points in 2D space of three functions, namely **Rastrigin**, **Sphere**, and **Ackley**. You need to implement three basic search algorithms, namely **grid search**, **random search** and **first descent local optimization**.

Each algorithm must be implemented as a function in Python. You should submit a pdf report with required information and your source code as a separate file for the algorithms.

This section describes the algorithms you are implementing. The second sections has instruction on how to run the selected functions in R, and the last sections includes example on how to run the same package inside Python.

Grid search

Implement a grid search algorithm to evaluate the three selected 2D functions on a discrete grid of points with a grid size of 1, within the specified bounds for each function. The point (0, 0) should **always** be included in the search. See the appendix or the provided python code to see how to find the default bounds for each function.

For each of the selected functions, the report should include:

- a) Number of points tested
- b) Coordinates and objective values for the minimum and maximum found

Random search

Implement a random search function that searches the 2D space uniformly randomly within the specified bounds for each function.

For each of the selected functions, the report should include:

- a) Mean objective value found over 1000 calls
- b) Coordinates and objective value for the minimum found

Local search

Implement a local search using **first descent**, which means that you move to the next solution as soon as the first neighbor you find is better than the current solution instead of checking all the neighbors and moving to the best one. Let the algorithm run for a maximum of 1000 iterations with a neighborhood size of

100. Define a neighbor of a solution (x,y) as $(x\pm\text{rand}(0.1), y\pm\text{rand}(0.1))$, where $\text{rand}(0.1)$ returns a uniformly random number from 0 to 0.1. The initial solution, from which you start the search, should be generated uniformly randomly inside the bounds of the function. The algorithm should stop after 1000 iterations or if it get stuck in local optimum. Meaning that none of the 100 generated neighbors are a better solution.

For each of the selected functions, run the algorithm 10 times and report:

- a) Best coordinates and objective value found over the 10 runs
- b) Mean objective value found over the 10 runs
- c) For each run, report the local minimum found, the number of iterations before reaching the local minimum, and the number of calls to the objective function.

Appendix

Python example

```
1 import numpy as np
2 import pymoo.problems as problem
3 import pymoo.visualization.fitness_landscape as
  pymooviz
4
5 #Import 3 problems
6 p1 = [problem.get_problem("rastrigin", n_var=2), "
  Rastrigin"]
7 p2 = [problem.get_problem("sphere", n_var=2), "Sphere"
  ]
8 p3 = [problem.get_problem("ackley", n_var=2), "Ackley"
  ]
9
10 #Visualization of the selected problems
11 for p in [p1, p2, p3]:
12     pymooviz.FitnessLandscape(p[0], angle=(45, 45),
13         _type="surface").show()
14
15 point = np.array([[1,0.5],
16     [0,0]])
17
18 #Evaluating each function at specific points and
19     printing bounds
20 for p in [p1, p2, p3]:
21     print(p[1], ":")
22     print(p[0].evaluate(point))
23     print("Lower and upper bounds:")
24     print(p[0].xl)
25     print(p[0].xu)
26     print("_")
```