Name and surname: _____

	Problem 1	Problem 2	Sum
Points	5,5	7	12,5

Midterm EXAM in Mathematical Modelling March 12, 2025

For each of tasks 1.-2. show your work and justify all your answers.

1. Let $\vec{F} : \mathbb{R}^3 \to \mathbb{R}^2$ be a vector function defined by

$$\vec{F}(x,y,z) = \begin{bmatrix} e^{x+2y+3z} \\ \sqrt[3]{xyz} \end{bmatrix}.$$

Using linear approximation at (1, 1, -1), compute the approximate value of $\vec{F}(1.1, 0.9, -0.9)$.



Name and surname: _

	Problem 1	Problem 2	Sum
Points			

Midterm EXAM in Mathematical Modelling March 12, 2025

For each of tasks 1.-2. show your work and justify all your answers.

1. Let $\vec{F} \colon \mathbb{R}^3 \to \mathbb{R}^2$ be a vector function defined by

$$\vec{F}(x,y,z) = \begin{bmatrix} e^{3x+2y+z} \\ \sqrt[3]{xyz} \end{bmatrix}.$$

Using linear approximation at (1, 1, -1), compute the approximate value of $\vec{F}(1.1, \not{\exists}, -0.9)$.



Name and surname: _____

	Problem 1	Problem 2	Sum
Points			

Midterm EXAM in Mathematical Modelling March 26, 2025

For each of tasks 1.-2. show your work and justify all your answers.

1. Let $\vec{F} \colon \mathbb{R}^3 \to \mathbb{R}^2$ be a vector function defined by

$$\vec{F}(x,y,z) = \begin{bmatrix} e^{x+2y+3z} \\ \sqrt[3]{xyz} \end{bmatrix}.$$

Using linear approximation at (1, 1, -1), compute the approximate value of $\vec{F}(1.1, 1.1, -0.9)$.



2. Let $\vec{G} \colon \mathbb{R}^3 \to \mathbb{R}^3$ be a vector function defined by

$$\vec{G}(x,y,z) = \begin{bmatrix} e^{3x+2y+z} \\ \sqrt[3]{xyz} \\ x \end{bmatrix}.$$

Using one step of Newton's method, approximate the solution of the equation $\vec{G}(x, y, z) = \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$ with the initial approximation $(x_0, y_0, z_0) = (1 + 1)$.

$$\begin{aligned} \overline{H}(x_{1}q_{1}e) &= \begin{pmatrix} e^{3y+2q_{1}+2} & -2\\ 3\sqrt{xy}e^{-1} + 2\\ y & -1 \end{pmatrix} \quad \text{Lookeing for } \overline{H}(x_{1}q_{1}e^{-1}) = 0, \\ \overline{H}(x_{1}q_{1}e) &= \begin{pmatrix} 3e^{3y+2q_{1}+2} & 2e^{3y+2q_{1}+2} & e^{-3y+2q_{1}e^{-1}}\\ \frac{y_{2}}{3\sqrt{(g_{2}g_{2})^{2}}} & \frac{x_{2}}{3\sqrt{(g_{2}g_{2})^{2}}} & \frac{x_{3}}{3\sqrt{(g_{2}g_{2})^{2}}} \\ \overline{H}(x_{1}q_{1}e^{-1}) &= \begin{pmatrix} 3e^{-1} & \frac{1}{3} & -\frac{1}{3}\\ \frac{1}{3} & -\frac{1}{3} & -\frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 3e^{-1} & \frac{1}{3} & -\frac{1}{3}\\ \frac{1}{3} & -\frac{1}{3} & -\frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 0 & 0 \end{pmatrix} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 1e^{-1} & \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1}{3}\\ 1 & 1e^{-1} & \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} \\ 1 & 1e^{-1} & \frac{1e^{-1}}{1} \\ \overline{H}(1-1-1) &= \begin{pmatrix} 1e^{-1} & \frac{1e^{-1}}{1} \\ \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} \\ \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} \\ \overline{H}(1-1-1) & \frac{1e^{-1}}{1} \\ \overline{H}(1-1-1) & \frac{1e^{-1}}{1} \\ \frac{1e^{-1}}{1} & \frac{1e^{-1}}{1} \\ \overline{H}(1-1-1) & \frac{1e^{-1}{$$

2. Let $\vec{G} \colon \mathbb{R}^3 \to \mathbb{R}^3$ be a vector function defined by

$$\vec{G}(x,y,z) = \begin{bmatrix} e^{x+2y+3z} \\ \sqrt[3]{xyz} \\ z \end{bmatrix}.$$

Using one step of Newton's method, approximate the solution of the equation $\vec{G}(x, y, z) = \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$ with the initial approximation $(x_0, y_0, z_0) = (1, 1, -1)$.

$$\begin{array}{c} (1) \rightarrow \overline{H} \left(x_{1} y_{1} z \right) = \begin{bmatrix} e^{x + 2y_{1} + 3z_{2} - 2} \\ 2(xy_{1} + 2) \\ y_{2} - 1 \end{bmatrix} \text{ Looking for } \overline{H} \left(x_{1} y_{1} z \right) = \overline{0} \\ \end{array}$$

2. Let $\vec{G} \colon \mathbb{R}^3 \to \mathbb{R}^3$ be a vector function defined by

$$\vec{G}(x,y,z) = \begin{bmatrix} e^{x+2y+3z} \\ \sqrt[3]{xyz} \\ y \end{bmatrix}.$$

Using one step of Newton's method, approximate the solution of the equation $\vec{G}(x, y, z) = \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$ with the initial approximation $(x_0, y_0, z_0) = (1, 1, -1)$.

$$\begin{aligned} H(x_{1}q_{1}z) &= \begin{bmatrix} e^{x+2y}t^{3}z^{2}-2\\ 3(xyz+2z)\\ y-1 \end{bmatrix} & \text{Lookulug for } H(x_{1}q_{1}z) = 0 \\ J_{q}^{*}(x_{1}y_{1}z) &= \begin{bmatrix} e^{x+2y}t^{3}z}\\ 3\frac{2}{2}(xyz)\\ y-1 \end{bmatrix} & \text{Lookulug for } H(x_{1}q_{1}z) = 0 \\ J_{q}^{*}(x_{1}y_{1}z) &= \begin{bmatrix} e^{x+2y}t^{3}z}\\ 3\frac{2}{2}(xyz)\\ 0 \end{bmatrix} & \frac{2e^{x+2y}t^{3}z}{3\frac{2}{2}(xyz)} & \frac{3e^{x+2y}t^{3}z}{3\frac{2}{2}(xyz)} \\ 0 \end{bmatrix} & J_{q}^{*}(t_{1}t_{1}-1) = \begin{bmatrix} 1\\ 1\\ 2\\ -\frac{1}{3} - \frac{1}{3} \\ 0 \end{bmatrix} & \begin{pmatrix} 1 & 2 & 3\\ -\frac{1}{3} - \frac{1}{3} \\ 0 \end{bmatrix} & \begin{pmatrix} 1 & 2 & 3\\ -\frac{1}{3} - \frac{1}{3} \\ 0 \end{bmatrix} & \begin{pmatrix} 1 & 0 & 2\\ -\frac{1}{3} - \frac{1}{3} \\ 0 \end{bmatrix} & \begin{pmatrix} 1 & 0 & 2\\ 0 & 1 & 0 \end{bmatrix} \\ & \begin{pmatrix} 1 & 0 & 2\\ 0 & 1 & 0 \end{bmatrix} & \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 & 3 & 0 \end{pmatrix} \\ & = \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 \end{bmatrix} & \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 & 0 & 1 \end{pmatrix} \\ & = \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 & 0 & 1 \end{pmatrix} \\ & = \begin{pmatrix} 1 & 0 & -2\\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} & \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 & 0 & 1\\ 0 & 0 & 1 \end{pmatrix} \\ & = \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 & 0 & 1\\ 0 & 0 & 1 \end{pmatrix} \\ & = \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 & 0 & 1\\ 0 & 0 & 1 \end{pmatrix} \\ & = \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 & 0 & 1\\ 0 & 0 & 1\\ 0 & 0 & 1 \end{pmatrix} \\ & = \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0 & 0 & 1\\ 0 & 0 & 1\\ 0 & 0 & 1 \end{pmatrix} \\ & = \begin{pmatrix} 1 & 0 & -2\\ 0 & 0 & 1\\ 0$$