

1) a) $t = ?$

$m = 8 \text{ kg} ; \mu_{TL} = 0,15 ; \alpha = 15^\circ ; h = 40 \text{ m}$

$\Sigma \vec{F} = m \vec{a} ;$

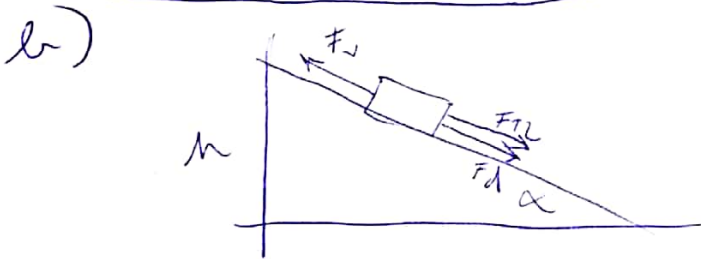
$|\Sigma \vec{F}|_{\parallel} = F_d - F_{TL} = F_{gy} \sin \alpha - F_{gy} \cos \alpha \cdot \mu_{TL} = m g (\sin \alpha - \cos \alpha \cdot \mu_{TL})$

$a = g (\sin \alpha - \cos \alpha \cdot \mu_{TL}) \approx 1,1 \text{ m/s}^2$

$v = v_0 + a t ; l = l_0 + \frac{a t^2}{2}$

$t^2 = \frac{2l}{a} ; t = \sqrt{\frac{2l}{a}} \approx \underline{\underline{16 \text{ s}}}$

$v = a t \approx \underline{\underline{18 \text{ m/s}}}$



$\frac{dv}{dt} = 0 \Rightarrow \Sigma \vec{F} = 0$

$\Rightarrow F_v = F_{TL} + F_d$

$= m a (\sin \alpha + \cos \alpha \cdot \mu_{TL})$

$\approx \underline{\underline{38 \text{ N}}}$

2. Sila na premikajoči nabit delec v magnetnem polju: $\vec{F} = e\vec{v} \times \vec{B}$

Pospešek (centripetalni) krožnega delca: $a = \frac{v^2}{r}$

$$\vec{v} \perp \vec{B}$$

$$|\vec{F}| = e|\vec{v}||\vec{B}|$$

$$F = evB = ma = m\frac{v^2}{r}$$

$$evB = \frac{mv^2}{r}$$

$$revB = mv^2$$

$$e = \frac{mv^2}{Br} = \frac{10^{-9} \text{ kg} \cdot 10^5 \text{ m/s}^2}{0,5 \text{ T} \cdot 0,15 \text{ m}} = \underline{\underline{1,3 \cdot 10^{-3} \text{ As}}}$$

$$F_c = evB = 1,3 \cdot 10^{-3} \text{ As} \cdot 10^5 \text{ m/s} \cdot 0,5 \text{ T} = \underline{\underline{66,7 \text{ N}}}$$

ALI:

$$F_c = \frac{mv^2}{r} = \frac{(10^5 \text{ m/s})^2 \cdot 10^{-9} \text{ kg}}{0,15 \text{ m}} = 66,7 \text{ N}$$

Nabit delec, ki preleti potencial U ima energijo $W_p = Ue$

$$Ue = \frac{mv^2}{2} \Rightarrow U = \frac{mv^2}{2e} = \frac{10^{-9} \text{ kg} \cdot 10^{10} \text{ m}^2/\text{s}^2}{2 \cdot 1,3 \cdot 10^{-3} \text{ As}} = \underline{\underline{3,8 \cdot 10^3 \text{ V}}}$$

3)

a) PLASTIČNA SE ŽELEZI

$$\Delta \vec{P} = 0; \Delta W \neq 0!$$

$$\vec{P}_Z = \vec{P}_K; \quad R m \omega_z^2 = \omega_z (\Sigma J)$$

$$\Sigma J = 4 \cdot J_K + J_m =$$

$$= 4 \cdot \frac{M}{4} R^2 + m R^2 = \frac{M R^2}{3} + m R^2$$

$$R m \omega_z^2 = \omega_z R^2 \left(\frac{M}{3} + m \right)$$

$$\omega_z = \frac{m \omega_z^2}{\frac{M}{3} + m} = \frac{\omega_z^2}{R} \left(1 + \frac{M}{m^3} \right) = \underline{\underline{1,8 \text{ s}^{-1}}}$$

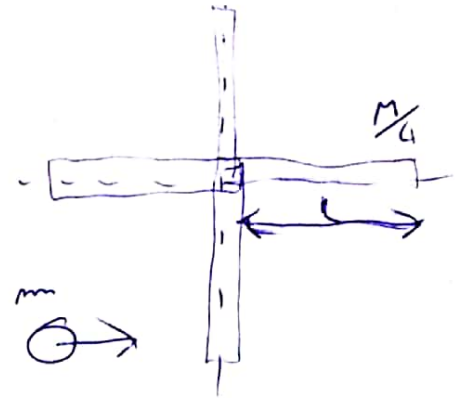
$M = 0,18 \text{ kg}; \quad m = 0,2 \text{ kg}, \quad R = 0,5 \text{ m}; \quad \omega_z = 20 \text{ rpm} = 5155 \text{ rad/s}$

$\omega_z = 2 \text{ rad/s} = 0,155 \text{ min}^{-1}$

b) $\Delta \vec{P} = 0 \quad \Delta W \neq 0!$

$$\vec{P}_Z = \vec{P}_K \quad R m \omega_z^2 = \omega_z (\Sigma J) + 2M(\omega_z R)$$

$$\omega_z = \frac{R m (\omega_z^2 + \omega_z R)}{4 \cdot \frac{M}{4} R^2} = 3 \cdot \frac{m (\omega_z^2 + \omega_z R)}{M R} = \underline{\underline{30,7 \text{ s}^{-1}}}$$



4. Napetost v prvem primeru je enaka napetosti v drugem primeru.

$$U_1 = U_2$$

$$Z_1 I_1 = Z_2 I_2$$

$$(R_1 + i\omega L) I_1 = (R_2 + i\omega L) I_2 \quad / \text{ vzamemo absolutno vrednost enačbe}$$

$$|R_1 + i\omega L| |I_1| = |R_2 + i\omega L| |I_2|$$

$$\sqrt{R_1^2 + (\omega L)^2} I_{10} = \sqrt{R_2^2 + (\omega L)^2} I_{20} \quad / \text{ kvadriramo}$$

$$(R_1^2 + (\omega L)^2) I_{10}^2 = (R_2^2 + (\omega L)^2) I_{20}^2$$

$$R_1^2 I_{10}^2 + \omega^2 L^2 I_{10}^2 = R_2^2 I_{20}^2 + \omega^2 L^2 I_{20}^2$$

$$R_1^2 I_{10}^2 - R_2^2 I_{20}^2 = \omega^2 L^2 I_{20}^2 - \omega^2 L^2 I_{10}^2$$

$$R_1 \quad \text{---} \quad \text{---} \quad = L^2 (\omega^2 I_{20}^2 - \omega^2 I_{10}^2)$$

$$L^2 = \frac{R_1^2 I_{10}^2 - R_2^2 I_{20}^2}{\omega^2 (I_{20}^2 - I_{10}^2)} =$$

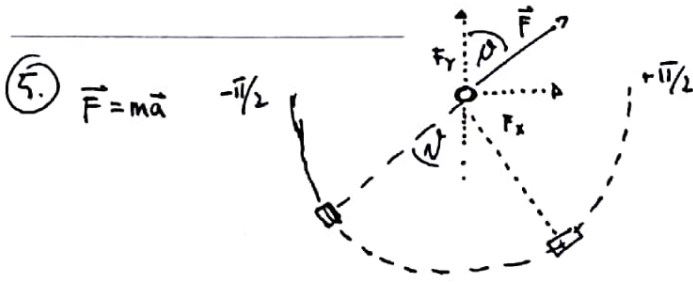
$$= \frac{(100 \Omega \cdot 0,1 \text{ A})^2 - (60 \Omega \cdot 0,15 \text{ A})^2}{(50 \text{ Hz} \cdot 2\pi)^2 ((0,15 \text{ A})^2 - (0,1 \text{ A})^2)} =$$

$$= \underline{\underline{0,12 \text{ H}}}$$

$$U_{10} = |Z_1| I_{10} = \sqrt{R_1^2 + (\omega L)^2} I_{10} = \sqrt{(100 \Omega)^2 + (2\pi \cdot 50 \text{ Hz})^2 \cdot (0,12 \text{ H})^2} \cdot 0,1 \text{ A} \cdot \sqrt{2} =$$

$$= \underline{\underline{15,1 \text{ V}}}$$

tu lahko računamo kar z efektivnimi tokovi, ker se $\sqrt{2}$ krajšajo



Vsaka komponenta F_x se odšteje z enako veliko in nasprotno usmerjeno komponento $-F_x$, ki jo povzroča delček kroga na drugi strani. F_y se seštevajo.

$$F = \int_{-\pi/2}^{\pi/2} dF \cdot \cos \vartheta$$

Polkrog razdelimo na segmente s kotno velikostjo $d\vartheta$ (in dolžino $r d\vartheta$). Vsak tak segment deluje s silo $dF = \frac{1}{4\pi\epsilon_0} \frac{e_1}{r} \cdot \frac{e_2}{\pi} d\vartheta$. e_1 je naboj delca, $e_2 \cdot \frac{d\vartheta}{\pi}$ pa je naboj segmenta polkroga.

$$F = \int_{-\pi/2}^{\pi/2} \frac{1}{4\pi\epsilon_0} \frac{e_1}{r} \frac{e_2}{\pi} \cdot \cos \vartheta d\vartheta = \frac{e_1 e_2}{4\pi^2 \epsilon_0 r} \int_{-\pi/2}^{\pi/2} \cos \vartheta d\vartheta = \frac{e_1 e_2}{4\pi^2 \epsilon_0 r} \sin \vartheta \Big|_{-\pi/2}^{\pi/2} =$$

$$= \frac{e_1 e_2}{4\pi^2 \epsilon_0 r} (1 + 1) = \frac{e_1 e_2}{4\pi \epsilon_0 r} \frac{2}{\pi} = 2,24 \cdot 10^{-3} \text{ N}$$

točkasti delci z nabojem e_2 faktor, ki ga dobimo pri polkrogu

$$a = \frac{F}{m} = \underline{\underline{0,75 \text{ m/s}^2}}$$

Končna hitrost je enaka začetni kinetični energiji. To hitrost doseže delec ko je od polkroga ~~oddaljen~~ neskončno oddaljen. Ker so vsi deli kroga od delca enako oddaljeni, integriranje ni potrebno. $W_p = \frac{1}{4\pi\epsilon_0} \frac{e_1 e_2}{r}$

$$W_{p2} + W_{k2} = W_{p1} + W_{k1}$$

$$\frac{1}{4\pi\epsilon_0} \frac{e_1 e_2}{r} + 0 = 0 + \frac{m v^2}{2} \Rightarrow v = \sqrt{\frac{1}{4\pi\epsilon_0} \frac{e_1 e_2}{r} \cdot \frac{2}{m}} = \underline{\underline{0,182 \text{ m/s}}}$$