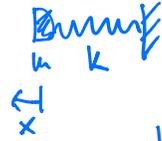


NIHANJE IN VALOVANJE

1) SISTEM

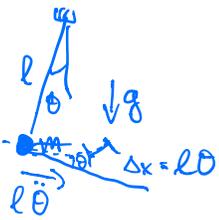
Stejeje, enačbe gibanje $F=ma$ (Newton)

Vzmetno nihalo 

Hookeov zakon: $F = -kx$
 $ma = m \frac{dv}{dt} = m \frac{d^2x}{dt^2} = -kx$

$$\ddot{x} + \frac{k}{m}x = 0$$

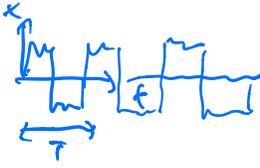
Matematično nihalo



$$m l \ddot{\theta} = -m g \sin \theta$$

$$\ddot{\theta} + \frac{g}{l} \sin \theta = 0$$

2) NIKANJE $x(t) = x(t+T)$
 periode T [s]



Pretakanje energije:
 kinetična \leftrightarrow potencialna

$$\nu = \frac{1}{T} \text{ [Hz]} \text{ frekvenca}$$

$$\omega = 2\pi\nu \text{ levozna frekvenca}$$

angl. angular frequency

Harmonično nihanje $x(t) = A \sin(\omega t + \varphi)$
 \uparrow amplituda \uparrow faza \uparrow fazni zamik

$$\sin(x + 2\pi) = \sin x$$

$$\omega T = 2\pi \quad \omega = \frac{2\pi}{T} = 2\pi\nu$$

dušenje $x(t) = A e^{-t/\tau} \sin(\omega t + \varphi)$

veljanje

relaksacijski čas

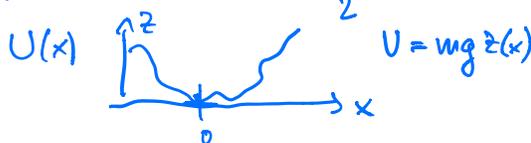
5% 1%



3) LINEARNOST

Taylorjev izrek $f(x) = f(0) + f'(0)x + \frac{f''(0)}{2}x^2 + \frac{f'''(0)}{3 \cdot 2}x^3 + \dots$

$$F=ma \quad F = -\frac{dU}{dx}$$



$$U = \frac{k}{2}x^2 + \dots \quad F = -\frac{dU}{dx} = -kx \rightarrow \text{linearizacija}$$

$$\ddot{\theta} + \frac{g}{l} \sin \theta = 0$$

$$\sin \theta = \theta - \frac{\theta^3}{6} + \dots$$

4) EULERJEVA ENAČBA

$$e^{i\theta} = \cos\theta + i\sin\theta$$

$$N! = N \cdot (N-1) \cdot \dots \cdot 2 \cdot 1$$

$$e^{i\theta} = 1 + i\theta - \frac{1}{2}\theta^2 - i\frac{1}{3!}\theta^3 + \frac{1}{4!}\theta^4 + \dots = \underbrace{\left(1 - \frac{\theta^2}{2} + \frac{\theta^4}{4!} + \dots\right)}_{\cos\theta} + i \underbrace{\left(\theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} + \dots\right)}_{\sin\theta}$$

$$z = x + iy$$

$$\begin{cases} \ddot{x} + \frac{k}{m}x = 0 \\ i\ddot{y} + i\frac{k}{m}y = 0 \end{cases}$$

$$\frac{d^2}{dt^2}(x+iy) + \frac{k}{m}(x+iy) = 0$$

$$\ddot{z} + \frac{k}{m}z = 0$$

$$x = a\sin(\omega t) + b\cos(\omega t)$$

$$z = A e^{i\omega t}$$

$$x = \operatorname{Re} z = \operatorname{Re} [z e^{i\omega t}]$$

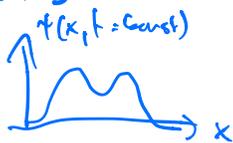
Polarni zapis
 $z = A e^{i\omega t}$ $A = |A| e^{i\varphi} = x_0 e^{i\varphi}$

$$z = x_0 e^{i\varphi} e^{i\omega t} \quad x = \operatorname{Re} [x_0 e^{i\varphi} e^{i\omega t}] = x_0 \operatorname{Re} e^{i(\omega t + \varphi)} = x_0 \cos(\omega t + \varphi)$$

Kompleksna amplituda $A = x_0 e^{i\varphi}$

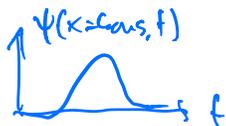
5) VALOVANJE, VALOVNA ENAČBA

$$\psi(x, t) \quad t = \text{konst.}$$

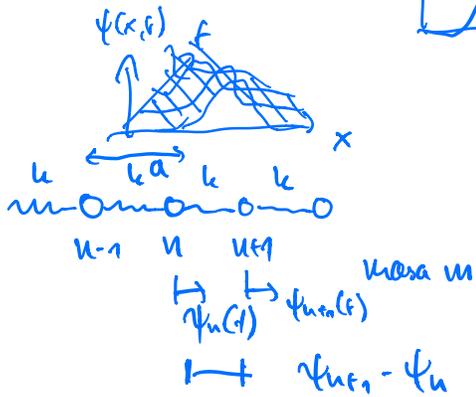


trdimna slika

$$x = \text{konst.}$$



časovni potek



$$m\ddot{\psi}_u = k(\psi_{u+1} - \psi_u) + k(\psi_{u-1} - \psi_u)$$

$$m\ddot{\psi}_u = k(\psi_{u+1} - 2\psi_u + \psi_{u-1})$$

$$f = \frac{df}{dt} \quad f' = \frac{df}{dx}$$

$$\ddot{f} = \frac{\partial^2 f}{\partial t^2} \quad f'' = \frac{\partial^2 f}{\partial x^2}$$

parcialni odvod

$$\psi(x, t) \quad \psi(x = na, t) = \psi_n(t)$$



$$f' = \frac{\partial f}{\partial x} = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x, t) - f(x, t)}{\Delta x}$$

$$= \lim_{\Delta x \rightarrow 0} \frac{f(x+\frac{\Delta x}{2}, t) - f(x-\frac{\Delta x}{2}, t)}{\Delta x}$$

$$f'' = \frac{\partial^2 f}{\partial x^2} = \lim_{\Delta x \rightarrow 0} \frac{\frac{\partial f}{\partial x}(x+\Delta x/2, t) - \frac{\partial f}{\partial x}(x-\Delta x/2, t)}{\Delta x}$$

$$= \lim_{\Delta x \rightarrow 0} \frac{[f(x+\Delta x, t) - f(x, t)] - [f(x, t) - f(x-\Delta x, t)]}{\Delta x^2}$$

$$\psi_{n+1} - 2\psi_n + \psi_{n-1} = \psi(na+a) - 2\psi(na) + \psi(na-a) = \frac{\partial^2 \psi}{\partial x^2} a^2$$

$$m\ddot{\psi}_n = ka^2 \frac{\partial^2 \psi}{\partial x^2}$$

$$\ddot{\psi}_n = \psi(x=na)$$

$$\frac{\partial^2 \psi(x, t)}{\partial t^2} = \left(\frac{ka^2}{m}\right) \frac{\partial^2 \psi(x, t)}{\partial x^2}$$

Val. meĉba $\boxed{\frac{\partial^2 \psi}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 \psi}{\partial t^2}} \rightarrow \text{linearua}$

$$\psi(x, t) = f(x-ct) + g(x+ct) \quad \text{splošna rešitev}$$

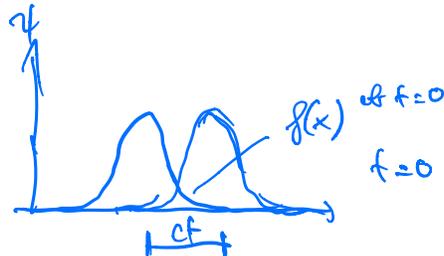
NACELO SUPERPOZICIJE!

$$\psi'' = f'' + g''$$

$$\frac{1}{c^2} \ddot{\psi} = \frac{1}{c^2} [(-c)^2 f'' + c^2 g''] = f'' + g'' \quad \checkmark$$

$$\psi = f(x-ct)$$

val v desno



$$\psi = g(x+ct)$$

val v levo

6) RAVNI VAL

$$\psi = A \sin[k(x-ct)]$$

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 \psi}{\partial t^2}$$

$$\psi(x,t) = f(x) e^{-i\omega t}$$

$$f''(x) e^{-i\omega t} = \frac{1}{c^2} f(x) (-i\omega)^2 e^{-i\omega t}$$

$$f'' + \frac{\omega^2}{c^2} f = 0$$

$$f = A e^{ikx}$$

$$A(i k)^2 e^{ikx} + \frac{\omega^2}{c^2} A e^{ikx} = 0$$

$$\frac{\omega^2}{c^2} = k^2$$

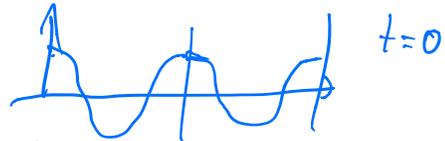
$$\boxed{\frac{\omega}{c} = k}$$

$$\omega = 2\pi\nu = 2\pi/T$$

$$\psi(x,t) = A e^{i(kx - \omega t)}$$

\longleftrightarrow

$$\psi(x,t) = A \cos(kx - \omega t)$$



$t=0$

λ : valovna dolžina

$$\frac{2\pi}{T} \cdot \frac{1}{c} = \frac{2\pi}{\lambda}$$

$$\frac{\lambda}{T} = c$$

$$\boxed{c = \frac{\lambda}{T}}$$

$$k \cdot \lambda = 2\pi \quad k = \frac{2\pi}{\lambda}$$

valovno število